Computer Graphics

Lecture #8

Projective Transformations

Relative Size Based on Distance

• Key idea of perspective: the size of an $y_s = rac{d}{z} \, y_s$



• Linear transformations:

x' = ax + by + cz

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• Affine transformations:

x' = ax + by + cz + d

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• Affine transformations: r' = ar + c

$$x' = ax + by + cz + d$$

• Our trick: using w in homogeneous coordinates as $x' = rac{a_1x+b_1y+c_1z+d_1}{ex+fy+gz+h}$ a denominator:

• Linear transformations:

$$x' = ax + by + cz$$

• Affine transformations: r' =

$$x' = ax + by + cz + d$$

- Our trick: using w in homogeneous coordinates as a denominator:
- Same denominator for all coordinates.

$$egin{array}{ll} x' &= rac{a_1x+b_1y+c_1z+d_1}{ex+fy+gz+h} \ y' &= rac{a_2x+b_2y+c_2z+d_2}{ex+fy+gz+h} \ z' &= rac{a_3x+b_3y+c_3z+d_3}{ex+fy+gz+h} \end{array}$$

Projective Transformations, or Homographies

$\left\lceil \tilde{x} \right\rceil$		$ig a_1$	b_1	c_1	d_1	$\begin{bmatrix} x \end{bmatrix}$
$ ilde{y} $		a_2	b_2	c_2	d_2	y
\tilde{z}		a_3	b_3	c_3	d_3	\boldsymbol{z}
$\lfloor \widetilde{w} \rfloor$		e	f	${oldsymbol{g}}$	h _	1

• Where we reinterpret coordinates by diving by w:

$$ig(x',y',z'ig) = (ilde x/ ilde w, ilde y/ ilde w, ilde z/ ilde w)$$

Equivalence of Points

- Key idea: all scalar multiples of a vector are the same!
- Equivalently: we're treating points as lines in one dimension higher

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\mathbf{x} \sim \alpha \mathbf{x}
for all \alpha \neq 0
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We will only divide by w when we want the Cartesian coordinates



Perspective Projection

Using Homographies for Perspective

• We can now replace:

$$y_s = rac{d}{z} y$$



• With:



Perspective Matrix

• Our matrix:

$$\mathbf{P} = \begin{bmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n+f & -fn \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

 Keeps near plane fixed, maps far plane to back of the box



• Effect on view rays / lines:



Note that affine transformation cannot do this because it keeps parallel lines parallel

 Perspective matrix effect on coordinates is nonlinear distortion in z:

$$\mathbf{P}\begin{bmatrix}x\\y\\z\\1\end{bmatrix}$$

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$$egin{bmatrix} n & 0 & 0 & 0 \ 0 & n & 0 & 0 \ 0 & 0 & n+f & -fn \ 0 & 0 & 1 & 0 \end{bmatrix} egin{bmatrix} x \ y \ z \ 1 \end{bmatrix}$$

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$$egin{bmatrix} n & 0 & 0 & 0 \ 0 & n & 0 & 0 \ 0 & 0 & n+f & -fn \ 0 & 0 & 1 & 0 \ \end{bmatrix} egin{bmatrix} x \ y \ z \ 1 \ \end{bmatrix} = egin{bmatrix} nx \ ny \ (n+f)z - fn \ z \ \end{bmatrix} \sim egin{bmatrix} rac{nw}{z} \ rac{ny}{z} \ n+f-rac{fn}{z} \ 1 \ \end{bmatrix}$$

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Perspective matrix effect on coordinates is nonlinear distortion in z:

$$egin{bmatrix} n & 0 & 0 & 0 \ 0 & n & 0 & 0 \ 0 & 0 & n+f & -fn \ 0 & 0 & 1 & 0 \ \end{bmatrix} egin{bmatrix} x \ y \ z \ 1 \end{bmatrix} = egin{bmatrix} nx \ ny \ (n+f)z - fn \ z \end{bmatrix} \sim egin{bmatrix} rac{nw}{z} \ n+f - rac{fn}{z} \ 1 \end{bmatrix} \ 1 \end{bmatrix}$$

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• But it does, however, preserve order in the z-coordinate (which will become useful very soon)

Perspective Projection Matrix

Concatenating the perspective matrix with the orthographic projection provides the perspective projection matrix:

 $\mathbf{M}_{ ext{per}} = \mathbf{M}_{ ext{orth}} \mathbf{P} \qquad \mathbf{M}_{ ext{per}} = egin{bmatrix} rac{2n}{r-l} & 0 & rac{l+r}{l-r} & 0 \ 0 & rac{2n}{t-b} & rac{b+t}{b-t} & 0 \ 0 & 0 & rac{f+n}{n-f} & rac{2fn}{f-n} \ 0 & 0 & 1 & 0 \end{bmatrix}$

 We can define *l*, *r*, *b*, and *t* relative to the near plane, since we keep it fixed

Putting it all together

construct M_vp construct M_per construct M_cam M = M_vp * M_per * M_cam for each 3D object 0 { O_screen = M * 0 draw(O_screen) }

Equivalently: $\mathbf{M} = \mathbf{M}_{vp} \mathbf{M}_{orth} \mathbf{P} \mathbf{M}_{cam}$

For a given vertex $\mathbf{a} = (x, y, z)$, $\mathbf{p} = \mathbf{M}\mathbf{a}$ should result in

drawing $(x_p/w_p, y_p/w_p, z_p/w_p)$ on the screen

Lec20 Required Reading

• FOCG, Ch. 8